

## TOPOLOGICAL STRUCTURE OF THE COINCIDENCE SET FOR ABSTRACT CLASSES OF MAPS

DONAL O'REGAN

School of Mathematics, Statistics and Applied Mathematics  
National University of Ireland, Galway Ireland  
donal.oregan@nuigalway.ie

**ABSTRACT.** The existence of a coincidence point is discussed in an abstract setting. In addition we consider the case when the coincidence set contains a continuum intersecting a given set.

**AMS (MOS) Subject Classification.** 54H25

**Keywords:** essential maps, continuation methods, homotopy, continua of coincidence points

### 1. INTRODUCTION

In this paper we present general results for homotopies  $H$  for which the maps  $H_t$  may be defined in different domains. Conditions are put not only to guarantee the existence of a coincidence point but also to guarantee that the coincidence set contains a continuum (i.e. a compact connected set) which intersects a given set. Our theory is based on the notion of  $\Phi$ -essentiality (see [1, 10] and the references therein). The results in this paper were motivated in part by results in [1, 3, 4, 8, 9, 11].

### 2. PRELIMINARIES

We recall some results from the literature. Let  $X$  be a completely regular topological space and  $V$  an open subset of  $X$ .

We consider classes **A** and **B** of maps.

**Definition 2.1.** We say  $F \in MA(\overline{V}, X)$  (respectively  $F \in B(\overline{V}, X)$ ) if  $F : \overline{V} \rightarrow 2^X$  and  $F \in \mathbf{A}(\overline{V}, X)$  (respectively  $F \in \mathbf{B}(\overline{V}, X)$ ); here  $2^X$  denotes the family of nonempty subsets of  $X$  and  $\overline{V}$  denotes the closure of  $V$  in  $X$ .

Fix a  $\Psi \in B(\overline{V}, X)$ .

**Definition 2.2.** We say  $F \in MA_{\partial V}(\overline{V}, X)$  if  $F \in MA(\overline{V}, X)$  with  $F(x) \cap \Psi(x) = \emptyset$  for  $x \in \partial V$ ; here  $\partial V$  denotes the boundary of  $V$  in  $X$ .

**Definition 2.3.** Let  $F \in MA_{\partial V}(\overline{V}, X)$ . We say  $F : \overline{V} \rightarrow 2^X$  is  $\Psi$ -essential in  $MA_{\partial V}(\overline{V}, X)$  if for every map  $J \in MA_{\partial V}(\overline{V}, X)$  with  $J|_{\partial V} = F|_{\partial V}$  there exists  $x \in V$  with  $J(x) \cap \Psi(x) \neq \emptyset$ .

The following result was established in [5, 10].

**Theorem 2.4.** *Let  $X$  be a completely regular (respectively normal) topological space,  $V$  an open subset of  $X$  and let  $F \in MA_{\partial V}(\overline{V}, X)$  be  $\Psi$ -essential in  $MA_{\partial V}(\overline{V}, X)$ . Suppose there exists a map  $H : \overline{V} \times [0, 1] \rightarrow 2^X$  with  $H(\cdot, \eta(\cdot)) \in MA(\overline{V}, X)$  for any continuous function  $\eta : \overline{V} \rightarrow [0, 1]$  with  $\eta(\partial V) = 0$ ,  $\Psi(x) \cap H_t(x) = \emptyset$  for any  $x \in \partial V$  and  $t \in (0, 1]$ ,  $H_0 = F$  and  $\{x \in \overline{V} : \Psi(x) \cap H(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$  is compact (respectively closed). Then there exists  $x \in V$  with  $\Psi(x) \cap H_1(x) \neq \emptyset$ ; here  $H_t(x) = H(x, t)$ .*

Next we present a homotopy result for  $\Psi$ -essential maps. To achieve this we need to change Definition 2.3 (see Definition 2.6 below).

**Definition 2.5.** Let  $X$  be a completely regular (respectively normal) topological space, and  $V$  an open subset of  $X$ . Let  $F, G \in MA_{\partial V}(\overline{V}, X)$ . We say  $F \cong G$  in  $MA_{\partial V}(\overline{V}, X)$  if there exists a map  $H : \overline{V} \times [0, 1] \rightarrow 2^X$  with  $H(\cdot, \eta(\cdot)) \in MA(\overline{V}, X)$  for any continuous function  $\eta : \overline{V} \rightarrow [0, 1]$  with  $\eta(\partial V) = 0$ ,  $H_t(x) \cap \Psi(x) = \emptyset$  for any  $x \in \partial V$  and  $t \in [0, 1]$ ,  $H_1 = F$ ,  $H_0 = G$  and

$$\{x \in \overline{V} : \Psi(x) \cap H(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is compact (respectively closed); here  $H_t(x) = H(x, t)$ .

The following conditions will be assumed in our next result:

$$(2.1) \quad \cong \text{ is an equivalence relation in } MA_{\partial V}(\overline{V}, X),$$

and for any map  $\Lambda \in MA_{\partial V}(\overline{V}, X)$  we have

$$(2.2) \quad \left\{ \begin{array}{l} \text{if there exists a map } J \in MA_{\partial V}(\overline{V}, X) \text{ with } J \cong \Lambda \\ \text{in } MA_{\partial V}(\overline{V}, X) \text{ and } J(x) \cap \Psi(x) = \emptyset \text{ for all } x \in \overline{V} \\ \text{and if } H : \overline{V} \times [0, 1] \text{ is a map with } H(\cdot, \eta(\cdot)) \in MA(\overline{V}, X) \\ \text{for any continuous function } \eta : \overline{V} \rightarrow [0, 1] \text{ with } \eta(\partial V) = 0, \\ H_t(x) \cap \Psi(x) = \emptyset \text{ for any } x \in \partial V \text{ and } t \in [0, 1], H_1 = \Lambda, H_0 = J \\ \text{and } \{x \in \overline{V} : \Psi(x) \cap H(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\} \\ \text{is compact (respectively closed) and if } \mu : \overline{V} \rightarrow [0, 1] \text{ is a} \\ \text{continuous map with } \mu(\partial V) = 0, \text{ then} \\ \{x \in \overline{V} : \emptyset \neq \Psi(x) \cap H(x, t\mu(x)) \text{ for some } t \in [0, 1]\} \text{ is closed.} \end{array} \right.$$

**Definition 2.6.** Let  $F \in MA_{\partial V}(\overline{V}, X)$ . We say  $F : \overline{V} \rightarrow 2^X$  is  $\Psi$ -essential in  $MA_{\partial V}(\overline{V}, X)$  if for every map  $J \in MA_{\partial V}(\overline{V}, X)$  with  $J|_{\partial V} = F|_{\partial V}$  and  $J \cong F$  in  $MA_{\partial V}(\overline{V}, X)$  there exists  $x \in V$  with  $J(x) \cap \Psi(x) \neq \emptyset$ .

The following result was established in [10].

**Theorem 2.7.** *Let  $X$  be a completely regular (respectively normal) topological space,  $V$  an open subset of  $X$  and assume (2.1) and (2.2) hold. Suppose  $F$  and  $G$  are two maps in  $MA_{\partial V}(\overline{V}, X)$  with  $F \cong G$  in  $MA_{\partial V}(\overline{V}, X)$ . Then  $F$  is  $\Psi$ -essential in  $MA_{\partial V}(\overline{V}, X)$  if and only if  $G$  is  $\Psi$ -essential in  $MA_{\partial V}(\overline{V}, X)$ .*

**Remark 2.8.** Another homotopy result without conditions (2.1) and (2.2) can be found in [6]: Let  $X$  be a completely regular (respectively normal) topological space,  $V$  an open subset of  $X$ ,  $F \in MA_{\partial V}(\overline{V}, X)$  and let  $G \in MA_{\partial V}(\overline{V}, X)$  be  $\Psi$ -essential in  $MA_{\partial V}(\overline{V}, X)$  (Definition 2.3). For any map  $R \in MA_{\partial V}(\overline{V}, X)$  with  $R|_{\partial V} = F|_{\partial V}$  assume there exists a map  $H^R : \overline{V} \times [0, 1] \rightarrow 2^X$  with  $H^R(\cdot, \eta(\cdot)) \in MA(\overline{V}, X)$  for any continuous function  $\eta : \overline{V} \rightarrow [0, 1]$  with  $\eta(\partial V) = 0$ ,  $\Psi(x) \cap H_t^R(x) = \emptyset$  for any  $x \in \partial V$  and  $t \in (0, 1)$  and  $\{x \in \overline{V} : \Psi(x) \cap H^R(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$  is compact (respectively closed) and  $H_0^R = G$ ,  $H_1^R = R$ ; here  $H_t^R(x) = H^R(x, t)$ . Then  $F$  is  $\Psi$ -essential in  $MA_{\partial V}(\overline{V}, X)$ . There is an analogue result also in [6] if  $G \in MA_{\partial V}(\overline{V}, X)$  is  $\Psi$ -essential in  $MA_{\partial V}(\overline{V}, X)$  (Definition 2.3) is changed to  $G \in MA_{\partial V}(\overline{V}, X)$  is  $\Psi$ -essential in  $MA_{\partial V}(\overline{V}, X)$  (Definition 2.6).

**Remark 2.9.** The ideas presented in this paper could be applied to other natural situations. Let  $X$  be a Hausdorff topological vector space,  $Y$  a topological vector space, and  $V$  an open subset of  $X$ . Also let  $L : \text{dom } L \subseteq X \rightarrow Y$  be a linear (not necessarily continuous) single valued map; here  $\text{dom } L$  is a vector subspace of  $X$ . Finally  $T : X \rightarrow Y$  will be a linear single valued map with  $L + T : \text{dom } L \rightarrow Y$  a bijection; for convenience we say  $T \in H_L(X, Y)$ . We say  $F \in MA(\overline{V}, Y; L, T)$  (respectively  $F \in B(\overline{V}, Y; L, T)$ ) if  $F : \overline{V} \rightarrow 2^Y$  and  $(L + T)^{-1}(F + T) \in MA(\overline{V}, X)$  (respectively  $(L + T)^{-1}(F + T) \in B(\overline{V}, X)$ ). Fix a  $\Phi \in B(\overline{V}, Y; L, T)$ . We say  $F \in MA_{\partial V}(\overline{V}, Y; L, T)$  if  $F \in MA(\overline{V}, Y; L, T)$  with  $(L + T)^{-1}(F + T)(x) \cap (L + T)^{-1}(\Psi + T)(x) = \emptyset$  for  $x \in \partial V$ . Now  $F \in MA_{\partial V}(\overline{V}, Y; L, T)$  is  $(L, T)\Psi$ -essential in  $MA_{\partial V}(\overline{V}, Y; L, T)$  if for every map  $J \in MA_{\partial V}(\overline{V}, Y; L, T)$  with  $J|_{\partial V} = F|_{\partial V}$  there exists  $x \in V$  with  $(L + T)^{-1}(J + T)(x) \cap (L + T)^{-1}(\Psi + T)(x) \neq \emptyset$  (this is the analogue of Definition 2.3). There are analogues of Theorem 2.4, Theorem 2.7 and Remark 2.8 in this situation; see [5, 6, 10] where the results and proofs are presented. For example the analogue of Theorem 2.4 in this situation is: Let  $X$  be a topological vector space (so automatically completely regular),  $Y$  a topological vector space,  $V$  an open subset of  $X$ ,  $L : \text{dom } L \subseteq X \rightarrow Y$  a linear single valued map and  $T \in H_L(X, Y)$ . Let  $F \in MA_{\partial V}(\overline{V}, Y; L, T)$  be  $(L, T)\Psi$ -essential in  $MA_{\partial V}(\overline{V}, Y; L, T)$ . Suppose there exists a map  $H : \overline{V} \times [0, 1] \rightarrow 2^Y$  with  $(L + T)^{-1}(H(\cdot, \eta(\cdot)) + T(\cdot)) \in MA(\overline{V}, X)$  for any continuous function  $\eta : \overline{V} \rightarrow [0, 1]$  with  $\eta(\partial V) = 0$ ,  $(L + T)^{-1}(H_t + T)(x) \cap (L + T)^{-1}(\Psi + T)(x) = \emptyset$  for any  $x \in \partial V$  and  $t \in (0, 1]$ ,  $H_0 = F$  (here  $H_t(x) = H(x, t)$ ) and  $D = \{x \in \overline{V} : (L + T)^{-1}(\Psi + T)(x) \cap (L + T)^{-1}(H_t + T)(x) \neq \emptyset \text{ for some } t \in [0, 1]\}$  is

compact. Then there exists  $x \in V$  with  $(L+T)^{-1}(H_1+T)(x) \cap (L+T)^{-1}(\Psi+T)(x) \neq \emptyset$ . If  $X$  is a normal topological vector space then the assumption that  $D$  is compact, can be replaced by  $D$  is closed. It is easy to state and prove analogues of the results in Section 3 in this situation; we leave the details to the reader.

**Remark 2.10.** It is of interest also to note other general classes of maps in the literature. Consider classes **A**, **B** and **D** of maps. We say  $F \in D(\bar{V}, X)$  (respectively  $F \in B(\bar{V}, X)$ ) if  $F : \bar{V} \rightarrow 2^X$  and  $F \in \mathbf{D}(\bar{V}, X)$  (respectively  $F \in \mathbf{B}(\bar{V}, X)$ ). We say  $F \in A(\bar{V}, X)$  if  $F : \bar{V} \rightarrow 2^X$  and  $F \in \mathbf{A}(\bar{V}, X)$  and there exists a selection  $\theta \in D(\bar{V}, X)$  of  $F$ . There are analogues of Theorem 2.4 and Remark 2.8 for these maps; see for example [7].

Recall a compact connected set is called a continuum. Whyburn's lemma from topology can be stated as follows.

**Theorem 2.11.** *Let  $A$  and  $B$  be disjoint closed subsets of a compact Hausdorff topological space  $K$  such that no connected component of  $K$  intersects both  $A$  and  $B$ . Then there exists a partition  $K = K_1 \cup K_2$  where  $K_1$  and  $K_2$  are disjoint compact sets containing  $A$  and  $B$  respectively.*

An easy consequence of Theorem 2.11 is the following (see [3]).

**Theorem 2.12.** *Let  $X$  be a metric space and  $K$  a compact subset of  $X$ . Assume that  $A$  and  $B$  are two disjoint closed subsets of  $K$  such that no connected component of  $K$  intersects both. Then there exists an open bounded set  $U$  such that*

$$A \subset U, \quad \bar{U} \cap B = \emptyset \quad \text{and} \quad \partial U \cap K = \emptyset.$$

### 3. MAIN RESULTS

In many applications results are needed for homotopies  $H$  for which the maps  $H_t$  may be defined on different domains. The idea is to reduce the study of this family to that of a new family (of course depending on the old one) defined on the same domain. For notational purposes let  $Z$  be a topological space and  $\Omega$  a subset of  $Z \times [0, 1]$ . We write  $\Omega_\lambda = \{x \in Z : (x, \lambda) \in \Omega\}$  to denote the section of  $\Omega$  at  $\lambda$ .

In our next results we assume  $E$  is a completely regular topological space and  $U$  an open subset of  $E \times [0, 1]$  (note  $E \times [0, 1]$  is a completely regular topological space). We begin by presenting some results which guarantee the existence of a coincidence point.

**Theorem 3.1.** *Let  $E$  be a completely regular topological space and  $U$  an open subset of  $E \times [0, 1]$ . Suppose  $N \in MA(\bar{U}, E)$  and fix  $\Phi : \bar{U} \rightarrow 2^E$  with  $\Phi^* \in B(\bar{U}, E \times [0, 1])$ ; here  $\Phi^*(x, \lambda) = (\Phi(x, \lambda), \lambda)$  for  $(x, \lambda) \in \bar{U}$ . Let  $H : \bar{U} \times [0, 1] \rightarrow 2^{E \times [0, 1]}$  be given*

by  $H(x, \lambda, \mu) = (N(x, \lambda), \mu)$  for  $(x, \lambda) \in \bar{U}$  and  $\mu \in [0, 1]$  and assume  $H(\cdot, \cdot, \eta(\cdot)) \in MA(\bar{U}, E \times [0, 1])$  for any continuous function  $\eta : \bar{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$ . Also suppose the following conditions are satisfied:

$$(3.1) \quad \begin{cases} D = \{(x, \lambda) \in \bar{U} : \Phi^*(x, \lambda) \cap H(x, \lambda, \mu) \neq \emptyset \text{ for some } \mu \in [0, 1]\} \\ \text{is compact} \end{cases}$$

$$(3.2) \quad \begin{cases} H_0 \text{ is } \Phi^*\text{-essential in } MA_{\partial U}(\bar{U}, E \times [0, 1]) \text{ (Definition 2.3);} \\ \text{here } H_0(x, \lambda) = H(x, \lambda, 0) = (N(x, \lambda), 0) \text{ for } (x, \lambda) \in \bar{U} \end{cases}$$

and

$$(3.3) \quad \Phi(x, \lambda) \cap N(x, \lambda) = \emptyset \quad \text{for } (x, \lambda) \in \partial U.$$

Then there exists  $x \in U_1 = \{y \in E : (y, 1) \in U\}$  with  $\Phi(x, 1) \cap N(x, 1) \neq \emptyset$ .

*Proof.* Suppose there exists  $(x_0, \lambda_0) \in \partial U$  and  $\mu_0 \in [0, 1]$  with  $\Phi^*(x_0, \lambda_0) \cap H(x_0, \lambda_0, \mu_0) \neq \emptyset$  i.e.  $(\Phi(x_0, \lambda_0), \lambda_0) \cap (N(x_0, \lambda_0), \mu_0) \neq \emptyset$ . Then  $\mu_0 = \lambda_0$  and  $\Phi(x_0, \lambda_0) \cap N(x_0, \lambda_0) \neq \emptyset$ , which contradicts (3.3). Thus

$$\Phi^*(x, \lambda) \cap H(x, \lambda, \mu) = \emptyset \quad \text{for } (x, \lambda) \in \partial U \text{ and } \mu \in [0, 1].$$

Now Theorem 2.4 (with  $X = E \times [0, 1]$ ,  $V = U$  and  $\Psi = \Phi^*$ ) guarantees that there exists  $(x, \lambda) \in U$  with  $\Phi^*(x, \lambda) \cap H(x, \lambda, 1) \neq \emptyset$  i.e.  $(\Phi(x, \lambda), \lambda) \cap (N(x, \lambda), 1) \neq \emptyset$  i.e.  $\Phi(x, \lambda) \cap N(x, \lambda) \neq \emptyset$  and  $\lambda = 1$  i.e.  $x \in U_1$  and  $\Phi(x, 1) \cap N(x, 1) \neq \emptyset$ .  $\square$

**Remark 3.2.** If  $E \times [0, 1]$  is a normal topological space then (3.1) can be changed to:  $D$  is closed.

**Theorem 3.3.** Let  $E$  be a completely regular topological space and  $U$  an open subset of  $E \times [0, 1]$ . Suppose  $N \in MA(\bar{U}, E)$  and fix  $\Phi : \bar{U} \rightarrow 2^E$  with  $\Phi^* \in B(\bar{U}, E \times [0, 1])$ ; here  $\Phi^*(x, \lambda) = (\Phi(x, \lambda), \lambda)$  for  $(x, \lambda) \in \bar{U}$ . Also suppose (2.1) and (2.2) hold with  $X = E \times [0, 1]$ ,  $V = U$  and  $\Psi = \Phi^*$ . Let  $H : \bar{U} \times [0, 1] \rightarrow 2^{E \times [0, 1]}$  be given by  $H(x, \lambda, \mu) = (N(x, \lambda), \mu)$  for  $(x, \lambda) \in \bar{U}$  and  $\mu \in [0, 1]$  and assume  $H(\cdot, \cdot, \eta(\cdot)) \in MA(\bar{U}, E \times [0, 1])$  for any continuous function  $\eta : \bar{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$ . In addition assume (3.1), (3.2) (with Definition 2.6) and (3.3) hold. Then  $H_1$  is  $\Phi$ -essential in  $MA_{\partial U}(\bar{U}, E \times [0, 1])$  (in particular there exists  $x \in U_1$  with  $\Phi(x, 1) \cap N(x, 1) \neq \emptyset$ ); here  $H_1(x, \lambda) = H(x, \lambda, 1) = (N(x, 1), 1)$  for  $(x, \lambda) \in \bar{U}$ .

*Proof.* As in Theorem 3.1 note

$$\Phi^*(x, \lambda) \cap H(x, \lambda, \mu) = \emptyset \text{ for } (x, \lambda) \in \partial U \text{ and } \mu \in [0, 1].$$

Also the conditions in the statement of Theorem 3.3 guarantees that  $H_0 \cong H_1$  in  $MA_{\partial U}(\bar{U}, E \times [0, 1])$ . Theorem 2.7 guarantees that  $H_1$  is  $\Phi$ -essential in  $MA_{\partial U}(\bar{U}, E \times [0, 1])$ .  $\square$

**Remark 3.4.** If  $E \times [0, 1]$  is a normal topological space then (3.1) can be changed to:  $D$  is closed.

**Remark 3.5.** We now consider the situation in Remark 2.9. Let  $E$  be a Hausdorff topological vector space,  $Y$  a topological vector space, and  $U$  an open subset of  $E \times [0, 1]$ . Also let  $L : \text{dom } L \subseteq E \rightarrow Y$  be a linear (not necessarily continuous) single valued map. Now let  $\mathbf{L} : \text{dom } \mathbf{L} = \text{dom } L \times [0, 1] \rightarrow Y \times [0, 1]$  be given by  $\mathbf{L}(y, \lambda) = (Ly, \lambda)$ . Let  $T : E \rightarrow Y$  be a linear single valued map with  $L + T : \text{dom } L \rightarrow Y$  a bijection and let  $\mathbf{T} : E \times [0, 1] \rightarrow Y \times [0, 1]$  be given by  $\mathbf{T}(y, \lambda) = (Ty, 0)$ . Notice  $(\mathbf{L} + \mathbf{T})^{-1}(y, \lambda) = ((L + T)^{-1}y, \lambda)$  for  $(y, \lambda) \in Y \times [0, 1]$ . There are analogues of Theorem 3.1 and Theorem 3.3 in this situation. For example the analogue of Theorem 3.1 is: Suppose  $N \in MA(\overline{U}, Y; L, T)$  and fix  $\Phi : \overline{U} \rightarrow 2^Y$  with  $\Phi^* \in B(\overline{U}, Y \times [0, 1]; \mathbf{L}, \mathbf{T})$ ; here  $\Phi^*(x, \lambda) = (\Phi(x, \lambda), \lambda)$  for  $(x, \lambda) \in \overline{U}$ . Let  $H : \overline{U} \times [0, 1] \rightarrow 2^{Y \times [0, 1]}$  be a map given by  $H(x, \lambda, \mu) = (N(x, \lambda), \mu)$  for  $(x, \lambda) \in \overline{U}$  and  $\mu \in [0, 1]$  and assume  $(\mathbf{L} + \mathbf{T})^{-1}(H(\cdot, \cdot, \eta(\cdot)) + \mathbf{T}) \in MA(\overline{U}, E \times [0, 1])$  for any continuous function  $\eta : \overline{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$ . Also suppose the following conditions are satisfied:

$$(3.4) \quad \begin{cases} D = \{(x, \lambda) \in \overline{U} : (\mathbf{L} + \mathbf{T})^{-1}(\Phi^* + \mathbf{T})(x, \lambda) \cap \\ (\mathbf{L} + \mathbf{T})^{-1}(H_\mu + \mathbf{T})(x, \lambda) \neq \emptyset \text{ for some } \mu \in [0, 1]\} \\ \text{is compact} \end{cases}$$

$$(3.5) \quad \begin{cases} H_0 \text{ is } (\mathbf{L}, \mathbf{T})\Phi^*\text{-essential in } MA_{\partial U}(\overline{U}, Y \times [0, 1]; \mathbf{L}, \mathbf{T}); \text{ here} \\ H_0(x, \lambda) = H(x, \lambda, 0) = (N(x, \lambda), 0) \text{ for } (x, \lambda) \in \overline{U} \end{cases}$$

and

$$(3.6) \quad \begin{cases} (L + T)^{-1}(\Phi + T)(x, \lambda) \cap (L + T)^{-1}(N + T)(x, \lambda) = \emptyset \\ \text{for } (x, \lambda) \in \partial U; \text{ here } (N + T)(x, \lambda) = N(x, \lambda) + T(x). \end{cases}$$

Then there exists  $x \in U_1 = \{y \in E : (y, 1) \in U\}$  with  $(L + T)^{-1}(\Phi + T)(x, 1) \cap (L + T)^{-1}(N + T)(x, 1) \neq \emptyset$ . If  $E \times [0, 1]$  is a normal topological vector space then  $D$  compact above can be changed to  $D$  closed.

Next we discuss the topological structure of the coincidence set.

**Theorem 3.6.** Let  $E$  be a completely regular topological space and  $U$  an open subset of  $E \times [0, 1]$ . Suppose  $N \in MA(\overline{U}, E)$  and fix  $\Phi : \overline{U} \rightarrow 2^E$  with  $\Phi^* \in B(\overline{U}, E \times [0, 1])$ ; here  $\Phi^*(x, \lambda) = (\Phi(x, \lambda), \lambda)$  for  $(x, \lambda) \in \overline{U}$ . Let  $H : \overline{U} \times [0, 1] \rightarrow 2^{E \times [0, 1]}$  be given by  $H(x, \lambda, \mu) = (N(x, \lambda), \mu)$  for  $(x, \lambda) \in \overline{U}$  and  $\mu \in [0, 1]$  and assume (3.2) (with Definition 2.3) and (3.3) hold. For any continuous map  $\mu : \overline{U} \rightarrow [0, 1]$  assume  $\Lambda \in MA(\overline{U}, E \times [0, 1])$  where

$$\Lambda(x, \lambda) = (N(x, \lambda), \mu(x, \lambda)) \text{ for } (x, \lambda) \in \overline{U}.$$

Also suppose

$$(3.7) \quad \begin{cases} \Omega = \{(x, \lambda) \in \bar{U} : \Phi(x, \lambda) \cap N(x, \lambda) \neq \emptyset\} \\ \text{is compact and } \Omega_1 \neq \emptyset; \end{cases}$$

here  $\Omega_t = \{x \in E : (x, t) \in \Omega\}$  for  $t \in [0, 1]$ . Then  $\Omega$  contains a continuum intersecting  $\Omega_0 \times \{0\}$  and  $\Omega_1 \times \{1\}$ .

*Proof.* Note  $A = \Omega_0 \times \{0\} \subseteq \Omega$  and  $B = \Omega_1 \times \{1\} \subseteq \Omega$  are closed and compact. If there is no continuum intersecting  $A$  and  $B$  then from Theorem 2.11,  $\Omega$  can be represented as  $\Omega = \Omega^* \cup \Omega^{**}$  where  $\Omega^*$  and  $\Omega^{**}$  are disjoint compact sets with  $A \subseteq \Omega^*$  and  $B \subseteq \Omega^{**}$ . Notice  $\Omega^*$  and  $\Omega^{**} \cup \partial U$  are closed and disjoint (note  $\Omega^* \cap \partial U = \emptyset$  since if there exists a  $(x, \lambda) \in \partial U$  and  $(x, \lambda) \in \Omega^*$  then (note  $(x, \lambda) \in \Omega^* \subseteq \Omega$ )  $\Phi(x, \lambda) \cap N(x, \lambda) \neq \emptyset$  which contradicts (3.3)). Now there exists a continuous map  $\mu : \bar{U} \rightarrow [0, 1]$  with  $\mu(\Omega^{**} \cup \partial U) = 0$  and  $\mu(\Omega^*) = 1$ . Let

$$\Lambda(x, \lambda) = (N(x, \lambda), \mu(x, \lambda)) \quad \text{for } (x, \lambda) \in \bar{U}.$$

From the statement of Theorem 3.6 note  $\Lambda \in MA(\bar{U}, E \times [0, 1])$  and in fact  $\Lambda \in MA_{\partial U}(\bar{U}, E \times [0, 1])$  since if there exists a  $(x, \lambda) \in \partial U$  with  $\Phi^*(x, \lambda) \cap \Lambda(x, \lambda) \neq \emptyset$  then  $(\Phi(x, \lambda), \lambda) \cap (N(x, \lambda), \mu(x, \lambda)) \neq \emptyset$  i.e.  $(\Phi(x, \lambda), \lambda) \cap (N(x, \lambda), 0) \neq \emptyset$  i.e.  $\Phi(x, \lambda) \cap N(x, \lambda) \neq \emptyset$  with  $\lambda = 0$ , and this contradicts (3.3). Note  $H_0(x, \lambda) = H(x, \lambda, 0) = (N(x, \lambda), 0)$  so

$$\Lambda|_{\partial U} = H_0|_{\partial U}$$

since if  $(x, \lambda) \in \partial U$  then  $\Lambda(x, \lambda) = (N(x, \lambda), \mu(x, \lambda)) = (N(x, \lambda), 0)$  because  $\mu(\Omega^{**} \cup \partial U) = 0$ . Now (3.2) guarantees that there exists a  $(x, \lambda) \in U$  with  $\Phi^*(x, \lambda) \cap \Lambda(x, \lambda) \neq \emptyset$  i.e.  $(\Phi(x, \lambda), \lambda) \cap (N(x, \lambda), \mu(x, \lambda)) \neq \emptyset$  i.e.  $\Phi(x, \lambda) \cap N(x, \lambda) \neq \emptyset$  and  $\lambda = \mu(x, \lambda)$ . Note  $(x, \lambda) \in \Omega$  since  $(x, \lambda) \in U$  and  $\Phi(x, \lambda) \cap N(x, \lambda) \neq \emptyset$ . Now either  $(x, \lambda) \in \Omega^*$  or  $(x, \lambda) \in \Omega^{**}$ . Suppose  $(x, \lambda) \in \Omega^*$ . Then  $\mu(x, \lambda) = 1$  so  $\lambda = \mu(x, \lambda) = 1$  and  $\Phi(x, 1) \cap N(x, 1) \neq \emptyset$  i.e.  $(x, 1) \in B \subseteq \Omega^{**}$  which contradicts  $(x, 1) = (x, \lambda) \in \Omega^*$ . Next suppose  $(x, \lambda) \in \Omega^{**}$ . Then  $\mu(x, \lambda) = 0$  so  $\lambda = \mu(x, \lambda) = 0$  and  $\Phi(x, 0) \cap N(x, 0) \neq \emptyset$  i.e.  $(x, 0) \in A \subseteq \Omega^*$  which contradicts  $(x, 0) = (x, \lambda) \in \Omega^{**}$ .  $\square$

**Remark 3.7.** We now consider the situation in Remark 2.9 (and Remark 3.5) and the corresponding result is: Suppose  $N \in A(\bar{U}, Y; L, T)$  and fix  $\Phi : \bar{U} \rightarrow 2^Y$  with  $\Phi^* \in B(\bar{U}, Y \times [0, 1]; \mathbf{L}, \mathbf{T})$ ; here  $\Phi^*(x, \lambda) = (\Phi(x, \lambda), \lambda)$  for  $(x, \lambda) \in \bar{U}$ . Let  $H : \bar{U} \times [0, 1] \rightarrow 2^{Y \times [0, 1]}$  be given by  $H(x, \lambda, \mu) = (N(x, \lambda), \mu)$  for  $(x, \lambda) \in \bar{U}$  and  $\mu \in [0, 1]$  and assume (3.5) and (3.6) hold. For any continuous map  $\mu : \bar{U} \rightarrow [0, 1]$  assume  $\Lambda \in MA(\bar{U}, Y \times [0, 1]; \mathbf{L}, \mathbf{T})$  where

$$\Lambda(x, \lambda) = (N(x, \lambda), \mu(x, \lambda)) \quad \text{for } (x, \lambda) \in \bar{U}.$$

Also suppose

$$(3.8) \quad \begin{cases} \Omega = \{(x, \lambda) \in \overline{U} : (L + T)^{-1}(\Phi + T)(x, \lambda) \cap \\ (L + T)^{-1}(N + T)(x, \lambda) \neq \emptyset\} \text{ is compact} \\ \text{and } \Omega_1 \neq \emptyset. \end{cases}$$

Then  $\Omega$  contains a continuum intersecting  $\Omega_0 \times \{0\}$  and  $\Omega_1 \times \{1\}$ .

In our next result (3.3) is not assumed.

**Theorem 3.8.** *Let  $E$  be a metric space and  $U$  an open subset of  $E \times [0, 1]$ . Suppose  $N \in MA(\overline{U}, E)$  and fix  $\Phi : \overline{U} \rightarrow 2^E$  with  $\Phi^* \in B(\overline{U}, E \times [0, 1])$ ; here  $\Phi^*(x, \lambda) = (\Phi(x, \lambda), \lambda)$  for  $(x, \lambda) \in \overline{U}$ . Assume*

$$(3.9) \quad \Phi(x, 0) \cap N(x, 0) = \emptyset \quad \text{for } (x, 0) \in \partial U.$$

Let  $H : \overline{U} \times [0, 1] \rightarrow 2^{E \times [0, 1]}$  be given by  $H(x, \lambda, \mu) = (N(x, \lambda), \mu)$  for  $(x, \lambda) \in \overline{U}$  and  $\mu \in [0, 1]$  and assume (3.2) (with Definition 2.3) and (3.7) hold. For any continuous map  $\mu : \overline{U} \rightarrow [0, 1]$  assume  $\Lambda \in MA(\overline{U}, E \times [0, 1])$  where

$$(3.10) \quad \Lambda(x, \lambda) = (N(x, \lambda), \mu(x, \lambda)) \quad \text{for } (x, \lambda) \in \overline{U}.$$

In addition for open bounded subsets  $W$  of  $U$  with  $\Omega_0 \times \{0\} \subseteq W \subseteq U$  (so  $\Phi(x, 0) \cap N(x, 0) = \emptyset$  for  $(x, 0) \in U \setminus W$ ),  $\partial W \cap \Omega = \emptyset$  and  $\overline{W} \cap (\partial U \cap \Omega) = \emptyset$  assume  $N \in MA(\overline{W}, E)$  and the following conditions holds:

$$(3.11) \quad H_0 \text{ is } \Phi^* \text{-essential in } MA_{\partial W}(\overline{W}, E \times [0, 1])$$

$$(3.12) \quad \begin{cases} \text{for any continuous map } \mu : \overline{W} \rightarrow [0, 1] \text{ assume} \\ \Lambda \in MA(\overline{W}, E \times [0, 1]) \text{ where } \Lambda(x, \lambda) = (N(x, \lambda), \mu(x, \lambda)) \\ \text{for } (x, \lambda) \in \overline{W} \end{cases}$$

and

$$(3.13) \quad \Sigma \text{ is closed and } \Sigma_1 \neq \emptyset;$$

here  $\Sigma = \{(x, \lambda) \in \overline{W} : \Phi(x, \lambda) \cap N(x, \lambda) \neq \emptyset\}$  and  $\Sigma_t = \{x \in E : (x, t) \in \Sigma\}$  for  $t \in [0, 1]$ . Then  $\Omega$  contains a continuum intersecting  $\Omega_0 \times \{0\}$  and  $(\partial U \cap \Omega) \cup (\Omega_1 \times \{1\})$ .

*Proof.* There are two cases to consider, namely  $\Omega \cap \partial U = \emptyset$  or  $\Omega \cap \partial U \neq \emptyset$ . If  $\Omega \cap \partial U = \emptyset$  then (3.3) holds so the result follows from Theorem 3.6. Now suppose  $\Omega \cap \partial U \neq \emptyset$ . Let  $A = \Omega_0 \times \{0\}$ ,  $B = \Omega_1 \times \{1\}$  and  $C = \Omega \cap \partial U (\neq \emptyset)$ . Notice  $C \subseteq \Omega$  is closed and (3.9) guarantees that  $C \cap A = \emptyset$ . Now from Theorem 2.11 either

- (1). there exists a continuum of  $\Omega$  which intersects  $A$  and  $C$  (and we are finished),
- or
- (2).  $\Omega = \Omega^* \cup \Omega^{**}$  where  $\Omega^*$  and  $\Omega^{**}$  are disjoint compact sets with  $A \subseteq \Omega^*$  and  $C \subseteq \Omega^{**}$ .



Suppose (2) occurs. From Theorem 2.12 there exists an open bounded set  $V$  with

$$(3.14) \quad \Omega^* \subseteq V, \quad \overline{V} \cap \Omega^{**} = \emptyset \quad \text{and} \quad \partial V \cap \Omega = \emptyset.$$

Let  $W = U \cap V$ . We now show

$$(3.15) \quad A \subseteq W \subseteq U, \quad \partial W \cap \Omega = \emptyset \quad \text{and} \quad \overline{W} \cap (\partial U \cap \Omega) = \emptyset.$$

Note  $A \subseteq W$  since  $A \subseteq \Omega^* \subseteq V$  and  $A \subseteq U$  from (3.9). Next notice that

$$\begin{aligned} \partial W &= (\overline{U \cap V}) \setminus (U \cap V) \subseteq (\overline{U} \cap \overline{V}) \setminus (U \cap V) \\ &= ((\overline{U} \setminus U) \cap \overline{V}) \cup ((\overline{V} \setminus V) \cap \overline{U}) \\ &= (\partial U \cap \overline{V}) \cup (\partial V \cap \overline{U}) \subseteq (\partial U \cap \overline{V}) \cup \partial V, \end{aligned}$$

and note  $\partial V \cap \Omega = \emptyset$  (see (3.14)) and  $(\partial U \cap \overline{V}) \cap \Omega = \emptyset$  (from (3.14) we have  $\overline{V} \cap \Omega^{**} = \emptyset$  and note  $C = \Omega \cap \partial U \subseteq \Omega^{**}$  so we have  $\overline{V} \cap \Omega \cap \partial U = \emptyset$ ) and so  $\partial W \cap \Omega = \emptyset$ . Finally notice  $\overline{W} \cap \Omega^{**} = \emptyset$  since  $\overline{W} \subseteq \overline{U} \cap \overline{V} \subseteq \overline{V}$  and  $\overline{V} \cap \Omega^{**} = \emptyset$  from (3.9), so  $\overline{W} \cap \Omega^{**} = \emptyset$  and  $C \subseteq \Omega^{**}$  implies  $\overline{W} \cap (\partial U \cap \Omega) = \emptyset$ . Thus (3.15) holds.

Let

$$\Sigma = \{(x, \lambda) \in \overline{W} : \Phi(x, \lambda) \cap N(x, \lambda) \neq \emptyset\}.$$

Note  $\partial W \cap \Sigma = \emptyset$  (see (3.15) and note  $\Sigma \subseteq \Omega$ ). Now Theorem 3.6 (note  $\Sigma$  is compact) implies that  $\Sigma$  contains a continuum intersecting  $\Sigma_0 \times \{0\}$  ( $\subseteq \Omega_0 \times \{0\}$ ) and  $\Sigma_1 \times \{1\}$  ( $\subseteq \Omega_1 \times \{1\}$ ) and our result follows.  $\square$

**Remark 3.9.** We now consider the situation in Remark 2.9 (and Remarks 3.5 and 3.7) and the corresponding result is: Let  $E$  be a metric space and  $U$  an open subset of  $E \times [0, 1]$ . Suppose  $N \in MA(\overline{U}, Y; L, T)$  and fix  $\Phi : \overline{U} \rightarrow 2^Y$  with  $\Phi^* \in B(\overline{U}, Y \times [0, 1]; \mathbf{L}, \mathbf{T})$ ; here  $\Phi^*(x, \lambda) = (\Phi(x, \lambda), \lambda)$  for  $(x, \lambda) \in \overline{U}$ . Assume

$$(3.16) \quad (L + T)^{-1}(\Phi + T)(x, 0) \cap (L + T)^{-1}(N + T)(x, 0) = \emptyset \quad \text{for } (x, 0) \in \partial U.$$

Let  $H : \overline{U} \times [0, 1] \rightarrow 2^{Y \times [0, 1]}$  be given by  $H(x, \lambda, \mu) = (N(x, \lambda), \mu)$  for  $(x, \lambda) \in \overline{U}$  and  $\mu \in [0, 1]$  and assume (3.5) and (3.8) hold. For any continuous map  $\mu : \overline{U} \rightarrow [0, 1]$  assume  $\Lambda \in MA(\overline{U}, Y \times [0, 1]; \mathbf{L}, \mathbf{T})$  where

$$(3.17) \quad \Lambda(x, \lambda) = (N(x, \lambda), \mu(x, \lambda)) \quad \text{for } (x, \lambda) \in \overline{U}.$$

In addition for open bounded subsets  $W$  of  $U$  with  $\Omega_0 \times \{0\} \subseteq W \subseteq U$ ,  $\partial W \cap \Omega = \emptyset$ , and  $\overline{W} \cap (\partial U \cap \Omega) = \emptyset$  assume  $N \in MA(\overline{W}, Y; L, T)$  and the following conditions hold:

$$(3.18) \quad H_0 \text{ is } (\mathbf{L}, \mathbf{T})\Phi^*\text{-essential in } MA_{\partial W}(\overline{W}, Y \times [0, 1]; \mathbf{L}, \mathbf{T})$$

$$(3.19) \quad \left\{ \begin{array}{l} \text{for any continuous map } \mu : \overline{W} \rightarrow [0, 1] \text{ assume} \\ \Lambda \in MA(\overline{W}, Y \times [0, 1]; \mathbf{L}, \mathbf{T}) \text{ where} \\ \Lambda(x, \lambda) = (N(x, \lambda), \mu(x, \lambda)) \text{ for } (x, \lambda) \in \overline{W} \end{array} \right.$$

and

$$(3.20) \quad \Sigma \text{ is closed and } \Sigma_1 \neq \emptyset;$$

here  $\Sigma = \{(x, \lambda) \in \overline{W} : (L + T)^{-1}(\Phi + T)(x, \lambda) \cap (L + T)^{-1}(N + T)(x, \lambda) \neq \emptyset\}$ . Then  $\Omega$  contains a continuum intersecting  $\Omega_0 \times \{0\}$  and  $(\partial U \cap \Omega) \cup (\Omega_1 \times \{1\})$ .

In our next result  $\{(x, \lambda) \in \overline{U} : \Phi(x, \lambda) \cap N(x, \lambda) \neq \emptyset\}$  is compact is not assumed. For convenience we assume  $E$  is a normed space (the proof when  $E$  is a metric space is similar).

**Theorem 3.10.** *Let  $E$  be a normed space and  $U$  an open subset of  $E \times [0, 1]$ . Suppose  $N \in MA(\overline{U}, E)$  and fix  $\Phi : \overline{U} \rightarrow 2^E$  with  $\Phi^* \in B(\overline{U}, E \times [0, 1])$ ; here  $\Phi^*(x, \lambda) = (\Phi(x, \lambda), \lambda)$  for  $(x, \lambda) \in \overline{U}$ . Assume (3.9) and the following condition holds:*

$$(3.21) \quad \Omega_0 \text{ is nonempty and compact;}$$

here  $\Omega_0 = \{x \in E : (x, 0) \in \Omega\}$  where  $\Omega = \{(x, \lambda) \in \overline{U} : \Phi(x, \lambda) \cap N(x, \lambda) \neq \emptyset\}$ . Let  $H : \overline{U} \times [0, 1] \rightarrow 2^{E \times [0, 1]}$  be given by  $H(x, \lambda, \mu) = (N(x, \lambda), \mu)$  for  $(x, \lambda) \in \overline{U}$  and  $\mu \in [0, 1]$ . In addition for open bounded subsets  $W$  of  $U$  with  $\Omega_0 \times \{0\} \subseteq W \subseteq U$  (so  $\Phi(x, 0) \cap N(x, 0) = \emptyset$  for  $(x, 0) \in U \setminus W$ ) assume  $N \in MA(\overline{W}, E)$  and the following conditions hold:

$$(3.22) \quad H_0 \text{ is } \Phi^* \text{-essential in } MA_{\partial W}(\overline{W}, E \times [0, 1])$$

$$(3.23) \quad \begin{cases} \text{for any continuous map } \mu : \overline{W} \rightarrow [0, 1] \text{ assume} \\ \Lambda \in MA(\overline{W}, E \times [0, 1]) \text{ where } \Lambda(x, \lambda) = (N(x, \lambda), \mu(x, \lambda)) \\ \text{for } (x, \lambda) \in \overline{W} \end{cases}$$

and

$$(3.24) \quad \begin{cases} \Sigma = \{(x, \lambda) \in \overline{W} : \Phi(x, \lambda) \cap N(x, \lambda) \neq \emptyset\} \\ \text{is compact and } \Sigma_1 \neq \emptyset. \end{cases}$$

Then  $\Omega$  contains a connected component intersecting  $\Omega_0 \times \{0\}$  and which either intersects  $(\partial U \cap \Omega) \cup (\Omega_1 \times \{1\})$  or is unbounded.

*Proof.* Since  $\Omega_0$  is compact there exists  $n_0 \in \mathbf{N}$  with  $\Omega_0 \subseteq B(0, n_0)$ . For  $n \geq n_0$  let

$$U^n = U \cap (B(0, n) \times [0, 1]) \quad \text{and} \quad \Omega^n = \{(x, \lambda) \in \overline{U}^n : \Phi(x, \lambda) \cap N(x, \lambda) \neq \emptyset\}.$$

Note (3.9) implies  $\Omega_0 \times \{0\} \subseteq U$  and as a result  $\Omega_0 \times \{0\} \subseteq U^n$ . Also note if there exists  $(x, 0) \in U \setminus U^n$  with  $\Phi(x, 0) \cap N(x, 0) \neq \emptyset$  then  $(x, 0) \in \Omega_0 \times \{0\} \subseteq U^n$ , a contradiction. Thus

$$\Phi(x, 0) \cap N(x, 0) = \emptyset \quad \text{for } (x, 0) \in U \setminus U^n.$$

For each  $n \geq n_0$ , Theorem 3.8 (with  $U^n$  replacing  $U$  and note (3.7) holds with  $U^n$  replacing  $U$  (see (3.24) with  $W = U^n$ )) guarantees that there exists  $(x_n, 0) \in$

$\Omega_0 \times \{0\}$  and a connected component  $\mathbf{C}_n$  of  $\Omega^n$  containing  $(x_n, 0)$  and intersecting  $(\partial U^n \cap \Omega^n) \cup (\Omega_1^n \times \{1\})$  (here  $\Omega_1^n = \{x \in E : (x, 1) \in \Omega^n\}$ ). Since  $\Omega_0$  is compact the sequence  $(x_n)$  has an accumulation point  $x_0 \in \Omega_0$ . Assume that there is NO connected component of  $\Omega$  intersecting  $\Omega_0 \times \{0\}$  and  $(\partial U \cap \Omega) \cup (\Omega_1 \times \{1\})$ . Let  $\mathbf{C}_0$  be the connected component containing  $x_0$  (and not intersecting  $(\partial U \cap \Omega) \cup (\Omega_1 \times \{1\})$ ).

Our result follows if we show  $\mathbf{C}_0$  is unbounded. Assume  $\mathbf{C}_0$  is bounded. Note  $\mathbf{C}_0 \subseteq \bar{U}$  and  $\mathbf{C}_0 \cap \partial U = \emptyset$  (since  $\mathbf{C}_0$  does not intersect  $(\partial U \cap \Omega) \cup (\Omega_1 \times \{1\})$ ) so  $\mathbf{C}_0 \subseteq U$ , and note  $\mathbf{C}_0, \Omega_0 \times \{0\}$  are closed and bounded and as a result we can choose an open bounded set  $V$  with

$$\mathbf{C}_0 \cup (\Omega_0 \times \{0\}) \subseteq V \subseteq U.$$

Suppose  $\partial V \cap \Omega = \emptyset$ . Note if there exists  $(x, 0) \in U \setminus V$  with  $\Phi(x, 0) \cap N(x, 0) \neq \emptyset$  then  $(x, 0) \in \Omega_0 \times \{0\} \subseteq V$ , a contradiction. Thus

$$\Phi(x, 0) \cap N(x, 0) = \emptyset \quad \text{for } (x, 0) \in U \setminus V.$$

Now Theorem 3.8 with  $V$  replacing  $U$  (note  $\tilde{\Omega}_0 \times \{0\} \subseteq V \subseteq U$  and  $\partial V \cap \tilde{\Omega} = \emptyset$  since  $\tilde{\Omega} \subseteq \Omega$ ) implies that  $\tilde{\Omega} = \{(x, \lambda) \in \bar{V} : \Phi(x, \lambda) \cap N(x, \lambda) \neq \emptyset\}$  has a connected component intersecting  $\tilde{\Omega}_0 \times \{0\}$  ( $\subseteq \Omega_0 \times \{0\}$ ) and  $\tilde{\Omega}_1 \times \{1\}$  ( $\subseteq \Omega_1 \times \{1\}$ ), which contradicts the assumption that there is no connected component of  $\Omega$  intersecting  $\Omega_0 \times \{0\}$  and  $(\partial U \cap \Omega) \cup (\Omega_1 \times \{1\})$ ; here  $\tilde{\Omega}_t = \{x \in E : (x, t) \in \tilde{\Omega}\}$  for  $t \in [0, 1]$ . Thus

$$\partial V \cap \Omega \neq \emptyset.$$

Note  $(x_0, 0) \in \Omega_0 \times \{0\} \subseteq V$  so  $(x_0, 0)$  and  $\partial V \cap \Omega$  are closed disjoint subsets of the compact set  $\tilde{\Omega}$  and the connected component of  $\tilde{\Omega}$  containing  $(x_0, 0)$  does not intersect  $\partial V \cap \Omega$  (since  $\mathbf{C}_0 \subseteq V$ ). Now from Theorem 2.12 there exists an open bounded neighborhood  $V_0$  of  $(x_0, 0)$  with

$$(3.25) \quad (x_0, 0) \in V_0, \quad \bar{V}_0 \cap (\Omega \cap \partial V) = \emptyset \quad \text{and} \quad \partial V_0 \cap \tilde{\Omega} = \emptyset.$$

Let  $W = V \cap V_0$ . Now  $W \subseteq V$  with

$$(3.26) \quad (x_0, 0) \in W \quad \text{and} \quad \partial W \cap \Omega = \emptyset$$

since  $\partial W \subseteq (\partial V \cap \bar{V}_0) \cup (\partial V_0 \cap \bar{V})$  and note  $(\partial V \cap \bar{V}_0) \cap \Omega = \bar{V}_0 \cap (\partial V \cap \Omega) = \emptyset$  from (3.25) and  $(\partial V_0 \cap \bar{V}) \cap \Omega = \partial V_0 \cap (\bar{V} \cap \Omega) = \partial V_0 \cap \tilde{\Omega} = \emptyset$  from (3.25).

Now  $V$  is bounded and  $W$  is an open neighborhood of  $(x_0, 0)$  so there exists a  $n_1 \geq n_0$  with

$$(x_{n_1}, 0) \in W \quad \text{and} \quad V \subseteq B(0, n_1) \times [0, 1].$$

Note  $(x_{n_1}, 0) \in W \cap \mathbf{C}_{n_1}$  so  $W \cap \mathbf{C}_{n_1} \neq \emptyset$ . Also note that  $\mathbf{C}_{n_1}$  meets  $(E \times [0, 1]) \setminus W$  since  $\mathbf{C}_{n_1}$  intersects  $(\partial U^{n_1} \cap \Omega^{n_1}) \cup (\Omega_1^{n_1} \times \{1\})$  (and does not intersect  $(\partial U \cap \Omega) \cup (\Omega_1 \times \{1\})$ ). Now  $\mathbf{C}_{n_1}$  is connected so  $\mathbf{C}_{n_1} \cap \partial W \neq \emptyset$ . This is a contradiction since  $\mathbf{C}_{n_1} \cap \partial W \subseteq \Omega^{n_1} \cap \partial W \subseteq \Omega \cap \partial W = \emptyset$  from (3.26).  $\square$

**Remark 3.11.** We now consider the situation in Remark 2.9 (and Remarks 3.5, 3.7 and 3.9) and the corresponding result is: Let  $E$  be a normed space and  $U$  an open subset of  $E \times [0, 1]$ . Suppose  $N \in MA(\overline{U}, Y; L, T)$  and fix  $\Phi : \overline{U} \rightarrow 2^Y$  with  $\Phi^* \in B(\overline{U}, Y \times [0, 1]; \mathbf{L}, \mathbf{T})$ ; here  $\Phi^*(x, \lambda) = (\Phi(x, \lambda), \lambda)$  for  $(x, \lambda) \in \overline{U}$ . Assume (3.16) and the following conditions holds:

$$(3.27) \quad \Omega_0 \text{ is nonempty and compact;}$$

here  $\Omega_0 = \{x \in E : (x, 0) \in \Omega\}$  where  $\Omega = \{(x, \lambda) \in \overline{U} : (L + T)^{-1}(\Phi + T)(x, \lambda) \cap (L + T)^{-1}(N + T)(x, \lambda) \neq \emptyset\}$ . Let  $H : \overline{U} \times [0, 1] \rightarrow 2^{Y \times [0, 1]}$  be given by  $H(x, \lambda, \mu) = (N(x, \lambda), \mu)$  for  $(x, \lambda) \in \overline{U}$  and  $\mu \in [0, 1]$ . In addition for open bounded subsets  $W$  of  $U$  with  $\Omega_0 \times \{0\} \subseteq W \subseteq U$  assume  $N \in MA(\overline{W}, Y; L, T)$  and the following conditions hold:

$$(3.28) \quad H_0 \text{ is } (\mathbf{L}, \mathbf{T})\Phi^*\text{-essential in } MA_{\partial W}(\overline{W}, Y \times [0, 1]; \mathbf{L}, \mathbf{T})$$

$$(3.29) \quad \begin{cases} \text{for any continuous map } \mu : \overline{W} \rightarrow [0, 1] \text{ assume} \\ \Lambda \in MA(\overline{W}, Y \times [0, 1]; \mathbf{L}, \mathbf{T}) \text{ where} \\ \Lambda(x, \lambda) = (N(x, \lambda), \mu(x, \lambda)) \text{ for } (x, \lambda) \in \overline{W} \end{cases}$$

and

$$(3.30) \quad \begin{cases} \Sigma = \{(x, \lambda) \in \overline{W} : (L + T)^{-1}(\Phi + T)(x, \lambda) \cap \\ (L + T)^{-1}(N + T)(x, \lambda) \neq \emptyset\} \text{ is compact} \\ \text{and } \Sigma_1 \neq \emptyset. \end{cases}$$

Then  $\Omega$  contains a connected component intersecting  $\Omega_0 \times \{0\}$  and which either intersects  $(\partial U \cap \Omega) \cup (\Omega_1 \times \{1\})$  or is unbounded.

## REFERENCES

- [1] M. Furi and M. P. Pera, On the existence of an unbounded connected set of solutions for nonlinear equations in Banach spaces, *Atti. Accad. Naz. Lincei Rend. Cl. Sci. Fis. Mat. Natur.* **67(1-2)** (1979), 31–38.
- [2] G. Gabor, L. Gorniewicz and M. Slosarski, Generalized topological essentiality and coincidence points of multivalued maps, *Set-Valued Anal.* **17** (2009), 1–19.
- [3] M. Martelli, Continuation principles and boundary value problems, in *Topological Methods for Ordinary Differential equations*, Lecture Notes in Math, **Vol. 1537**, Springer, Berlin, 1993, 32–73.
- [4] J. Mawhin, Continuation theorems and periodic solutions of ordinary differential equations, in *Topological Methods in Differential Equations and Inclusions*, NATO ASI Series C, **Vol. 472**, Kluwer Academic Publishers, Dordrecht, 1995, 291–375.
- [5] M. Jleli, D. O'Regan and B. Samet, Topological coincidence principles, *Journal of Nonlinear Science and Applications*, to appear
- [6] M. Jleli, D. O'Regan and B. Samet, A homotopy approach to coincidence theory, *Dynamic Systems and Applications* **25** (2016), 393–408.
- [7] D. O'Regan, Abstract Leray–Schauder type alternatives and extensions, submitted.

- [8] D. O'Regan, Coincidence theory for multimaps, *Appl. Math. Comput.* **219** (2012), 2026–2034.
- [9] D. O'Regan, On the existence of connected sets of solutions for nonlinear operators, *Fixed Point Theory* **15** (2014), 180–198.
- [10] D. O'Regan, Generalized coincidence theory for set valued maps, *Journal of Nonlinear Science and Applications* **10** (2017), 855–864.
- [11] D. O'Regan and R. Precup, Theorems of Leray–Schauder Type and Applications, *Taylor and Francis Publishers*, London, 2002.